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# IMPROVING THE MULTI-TASKS DISTRIBUTION IN MULTI-ROBOT SYSTEMS



LAP Lambert Academic Publishing Jun 2013, 2013. Taschenbuch. Book Condition: Neu. 220x150x8 mm. This item is printed on demand - Print on Demand Neuware - This work study the coordination of multi-robot systems, in particular, addresses the problem of the distribution of heterogeneous multi-tasks. The main interest in these systems is to understand how from simple rules inspired by the division of labor in social insects, a group of robots can perform tasks in an organized and coordinated way. We...

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- Authored by Yadira Quiñonez
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